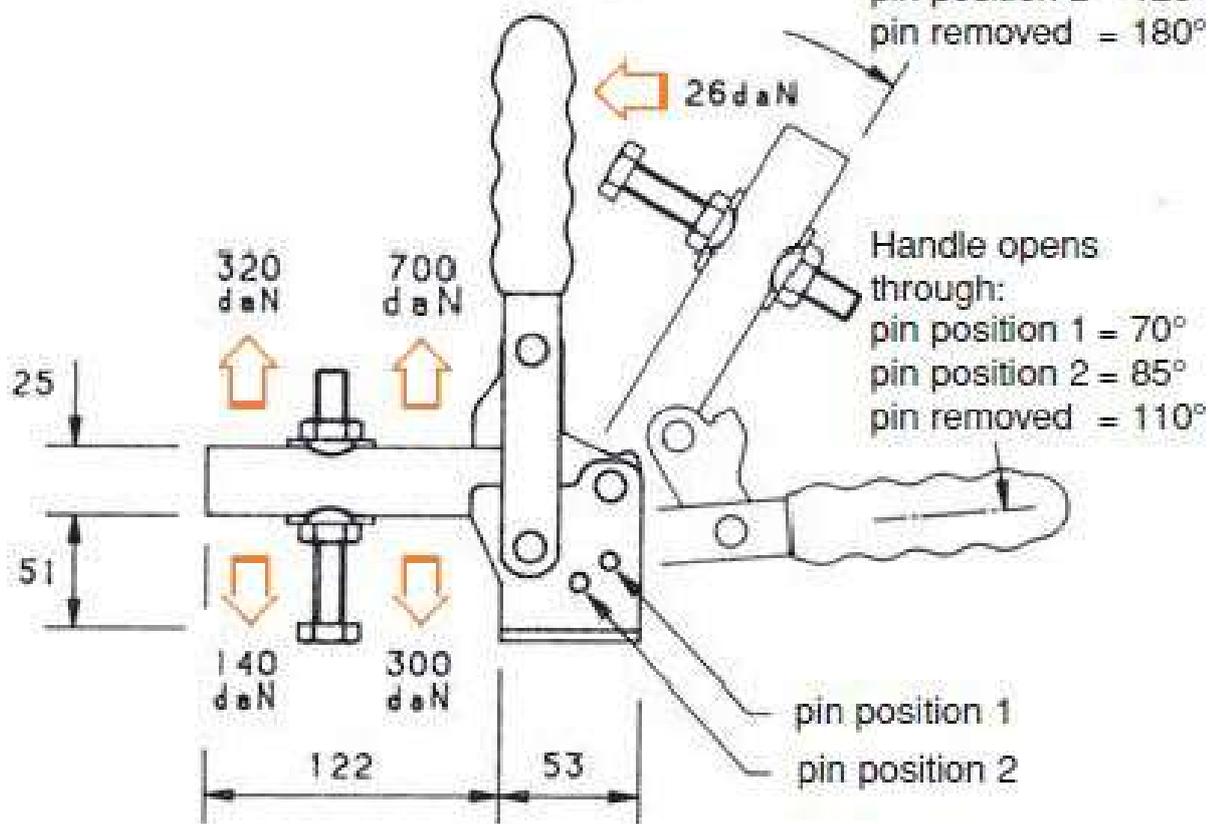
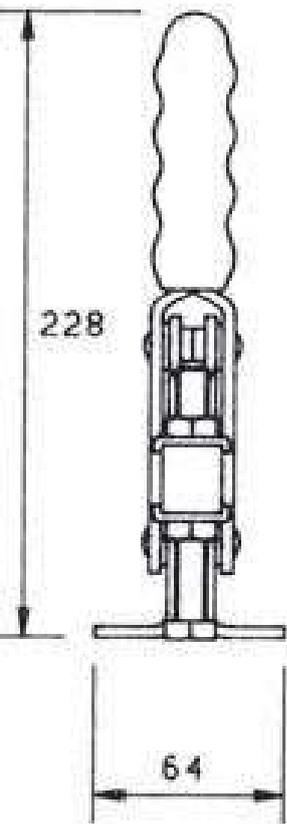


Arm opens through:
 pin position 1 = 90°
 pin position 2 = 125°
 pin removed = 180°



Handle opens through:
 pin position 1 = 70°
 pin position 2 = 85°
 pin removed = 110°